

Mapping and migrating reflected ground-roll

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Advisor: Dr. Stewart

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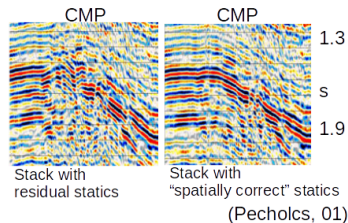
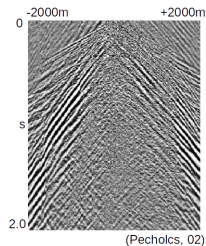


Outline: Ground-roll reflection

- Motivation
- Theory
- 2D fault imaging "in-line"
 - Synthetics
 - Field result
- 3D fault imaging "off-line"
 - Synthetics
- Summary

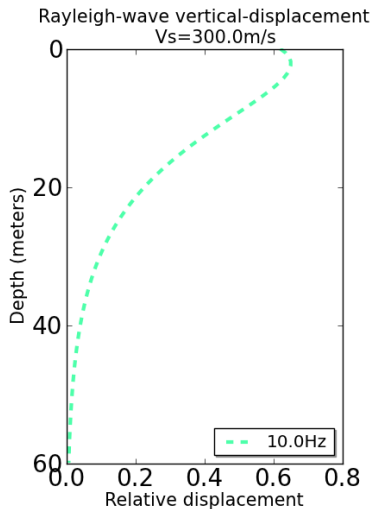
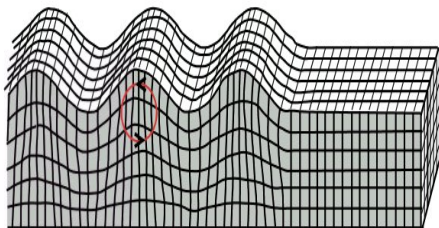
Motivation

- Identify vertical-ish features
- Image lateral heterogeneity
- Determine velocity and statics
- Design better reject filters
- Discover near-surface anomalies



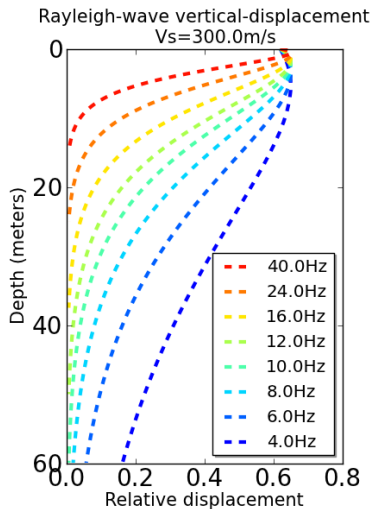
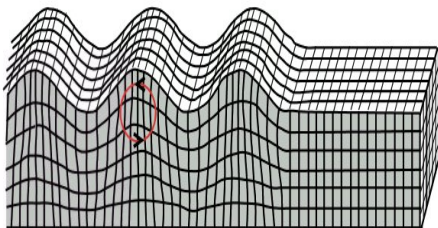
Theory

Ground-roll (Rayleigh-wave)

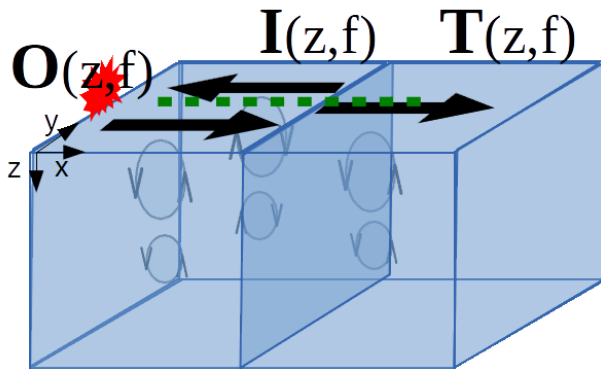


Theory

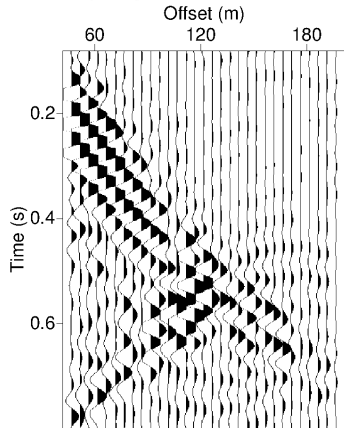
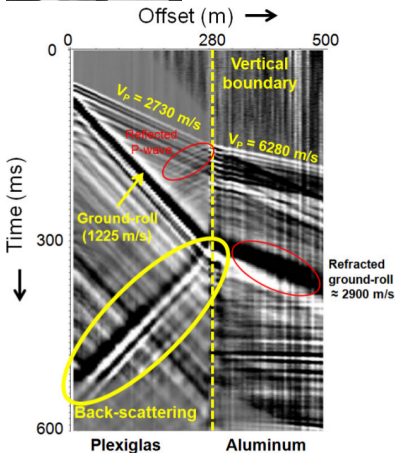
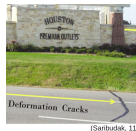
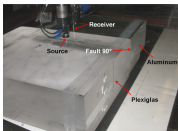
Ground-roll (Rayleigh-wave)



Back-reflected ground-roll

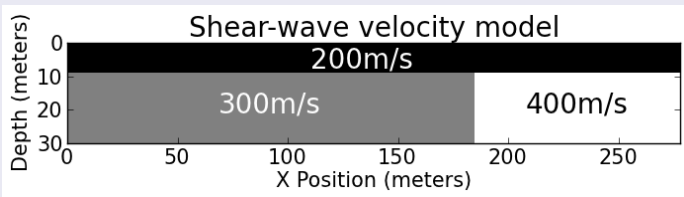


Back-reflected ground-roll



2D fault imaging

Synthetic model and survey parameters

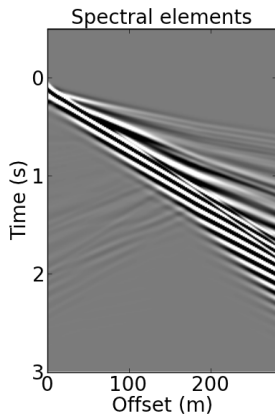


Source	10 Hz Ricker
Receiver	vertical component
Source interval	10 m
Receiver interval	1 m

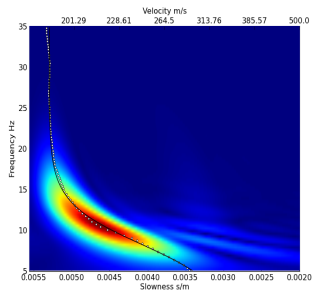
2D fault imaging

For dispersive surface-waves

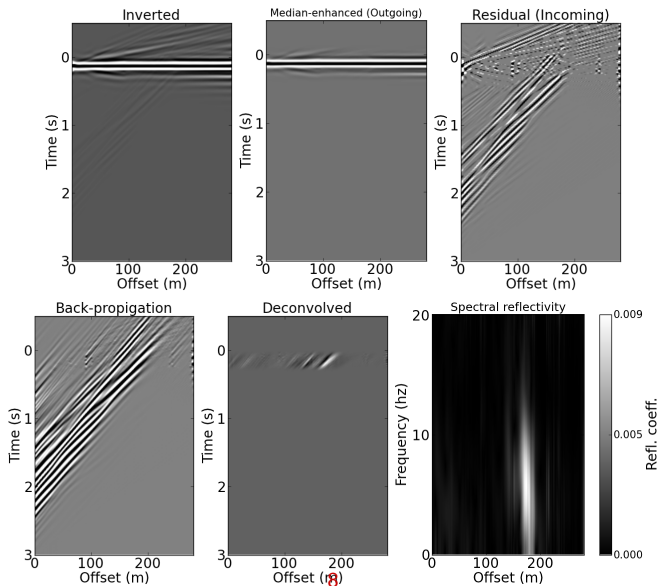
Phase-velocity is a function of frequency.



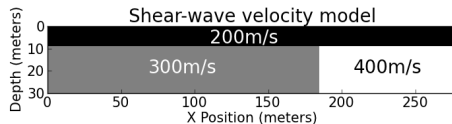
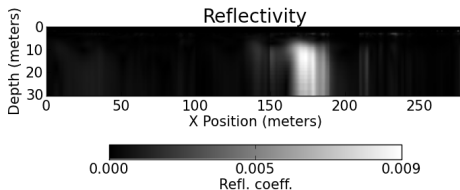
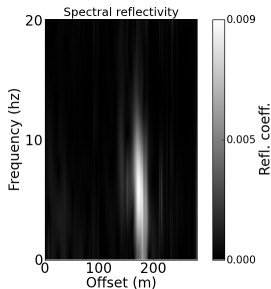
Extracted dispersion curve



2D fault imaging: Processing

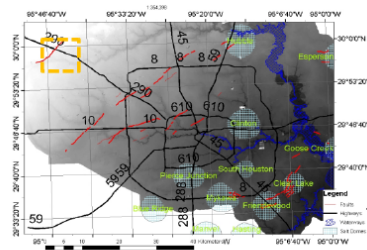
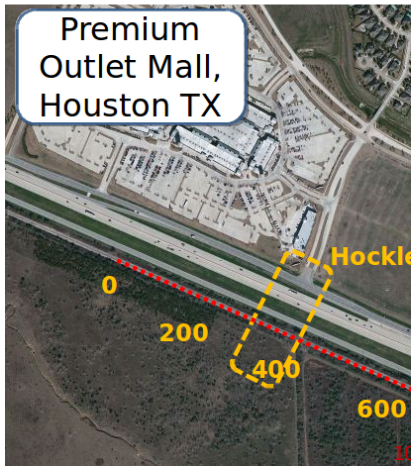


Reflectivity: Depth mapping

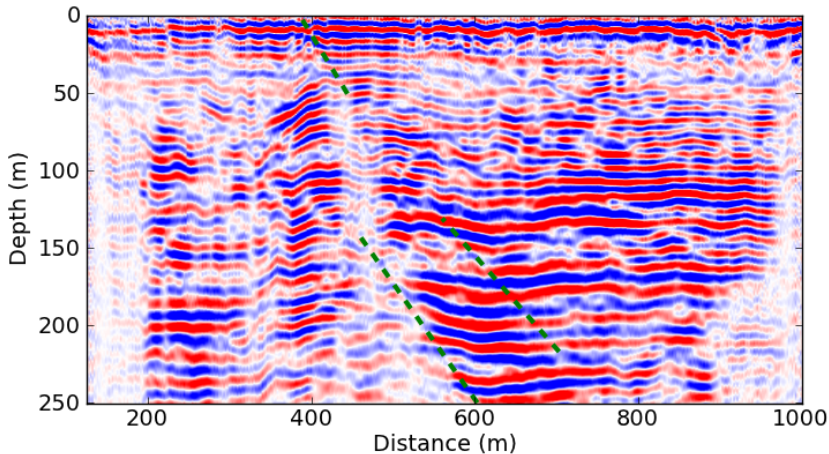


Field

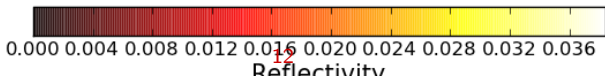
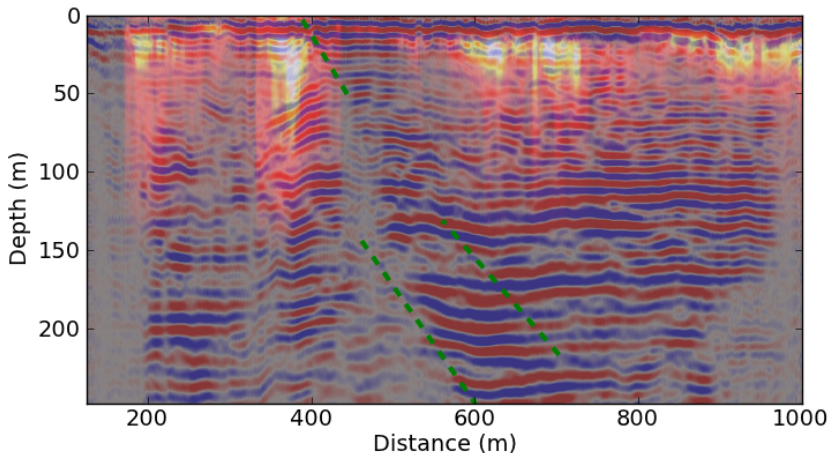
Source vertical vib.
 Receiver vertical component processed
 Source interval 5 m
 Receiver interval 5 m



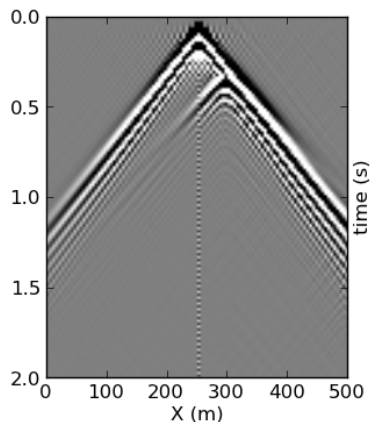
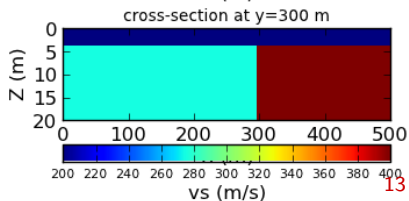
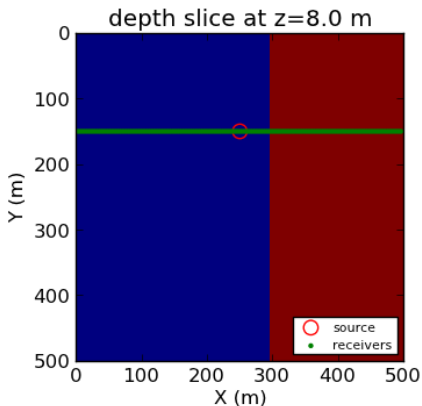
Field result



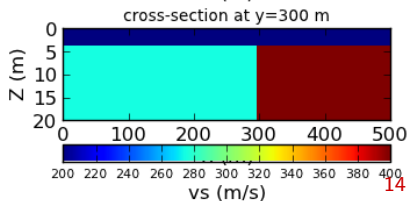
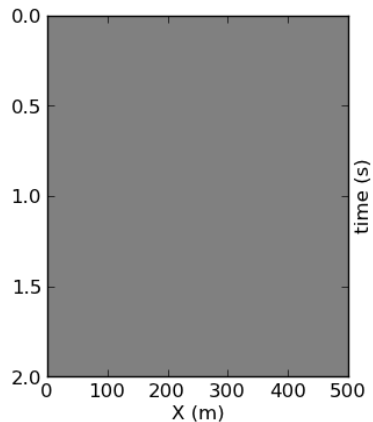
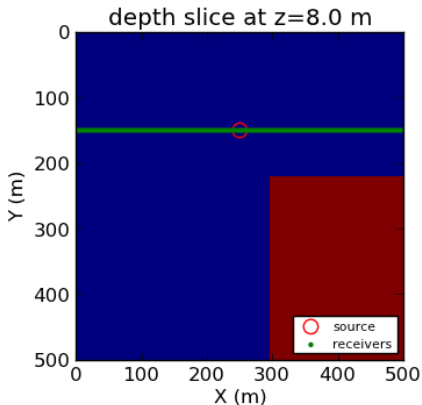
Field result



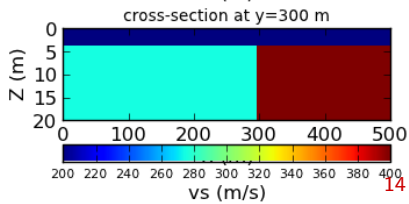
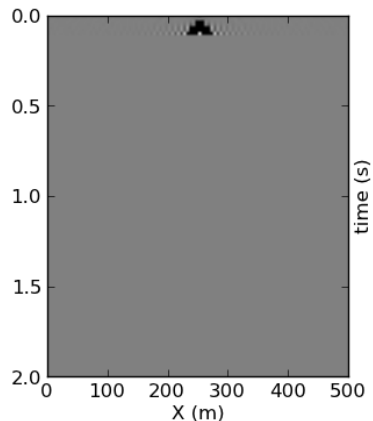
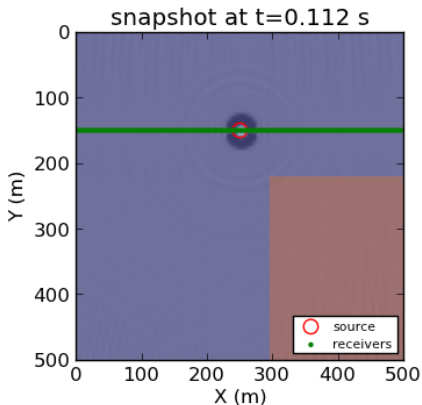
Fault in-line vs. off-line



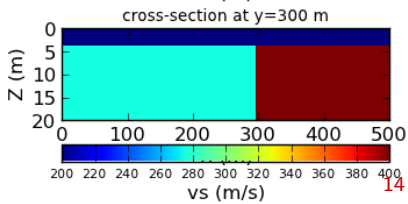
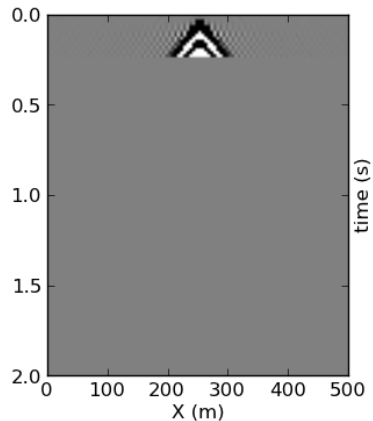
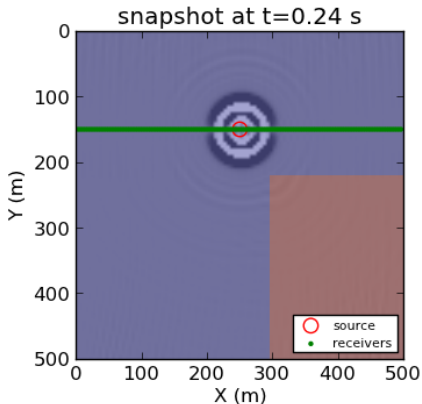
Fault "off-line"



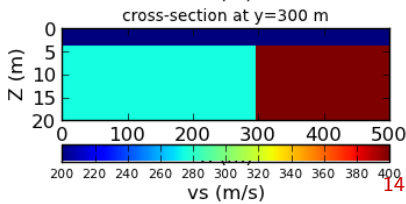
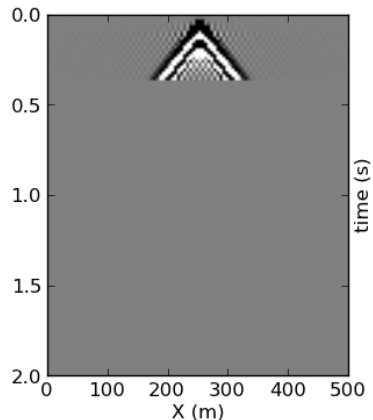
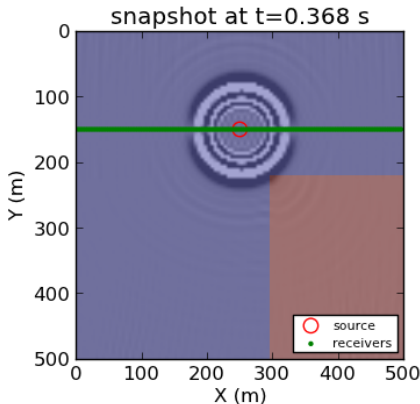
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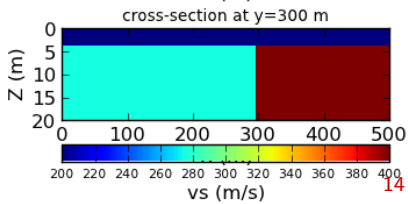
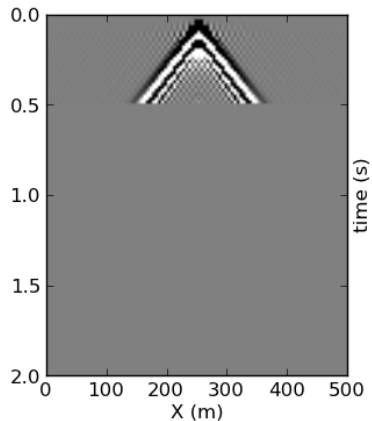
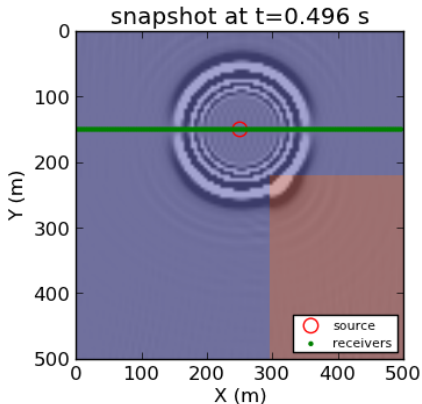
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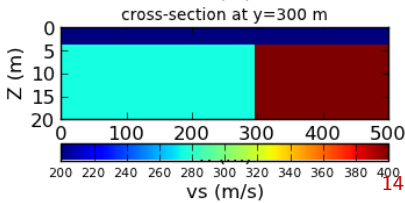
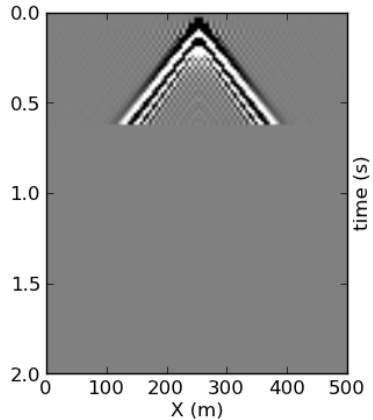
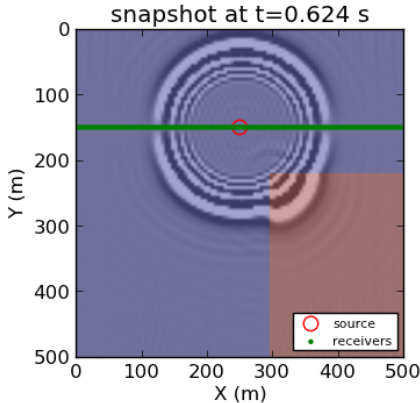
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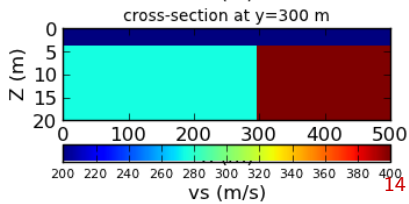
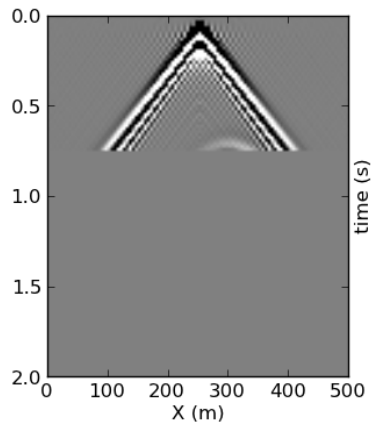
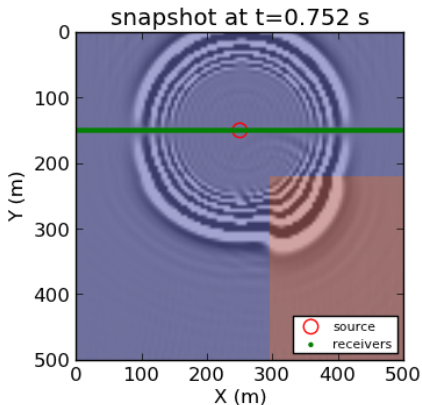
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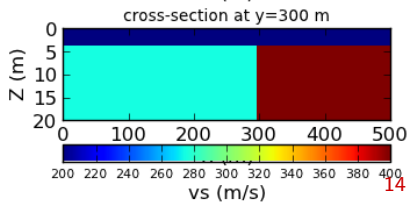
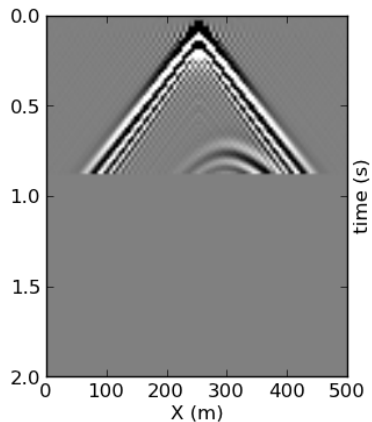
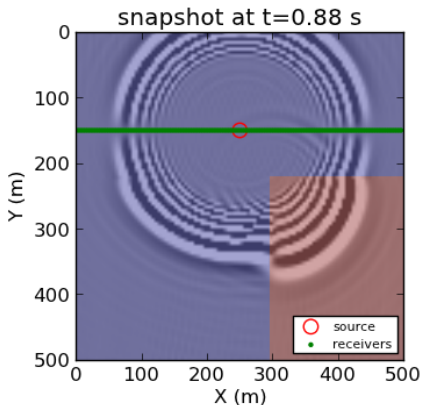
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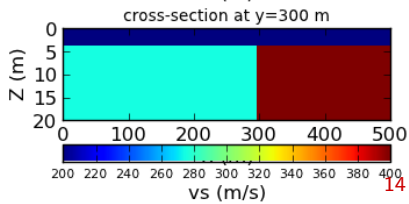
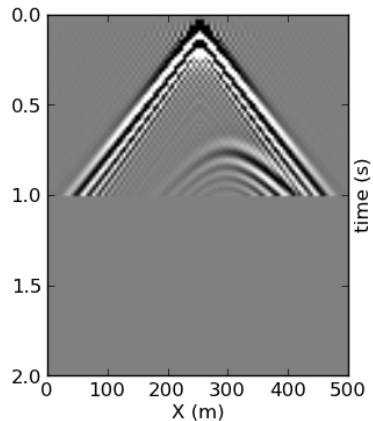
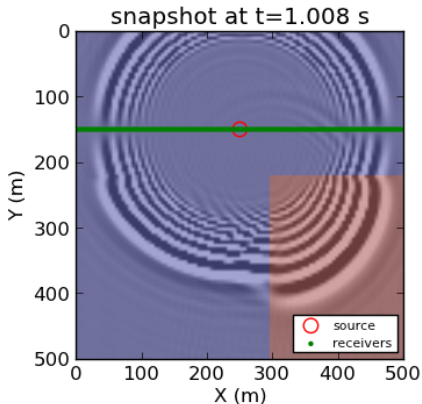
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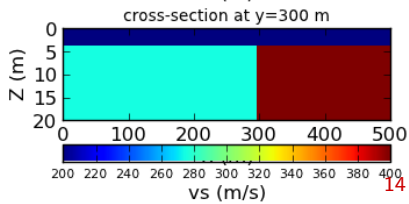
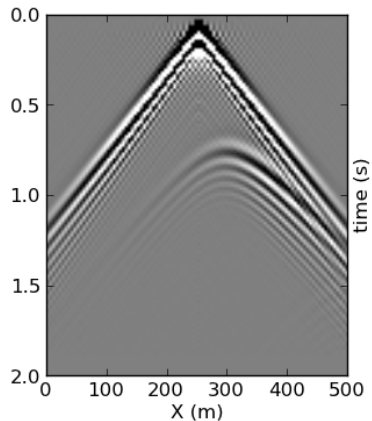
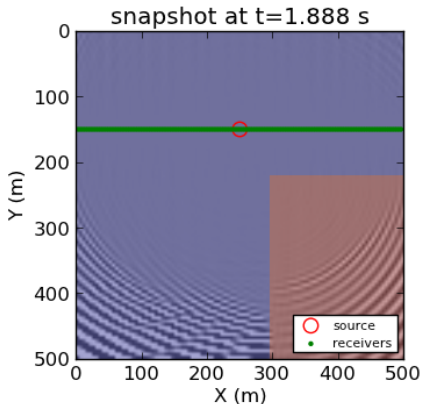
Fault "off-line"



Fault "off-line"



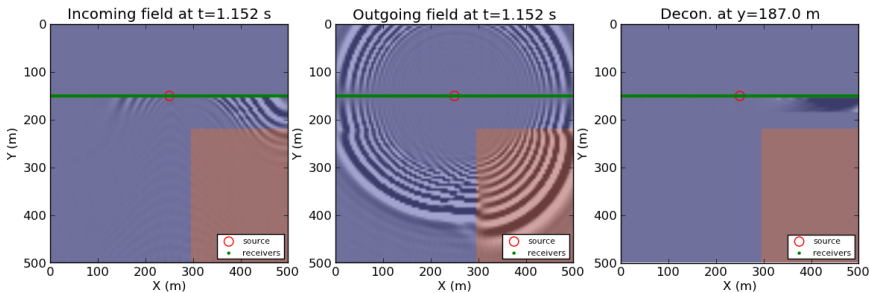
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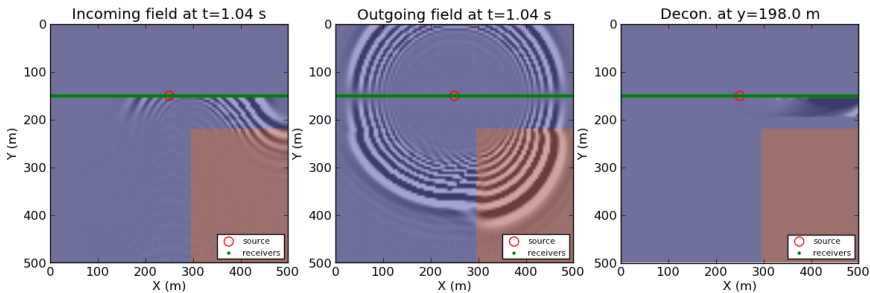
Ground-roll migration

- One-way split-step phase-shift (Stoffa, 90)
 - 2D X-Y (propagation in Y)
 - Modified for dispersion
 - Imaging condition - deconvolution

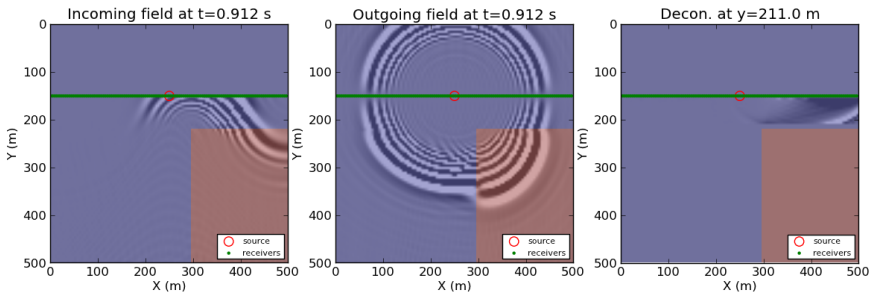
Ground-roll migration



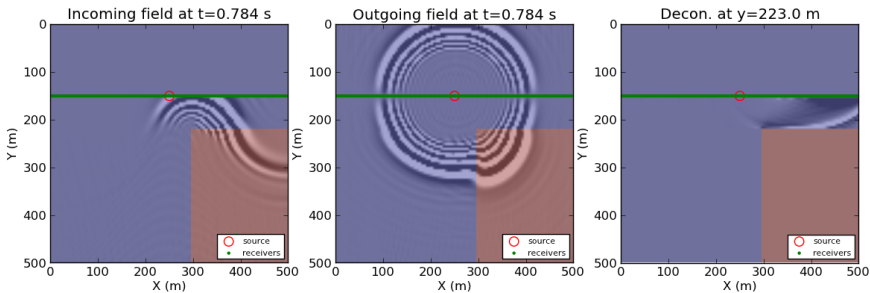
Ground-roll migration



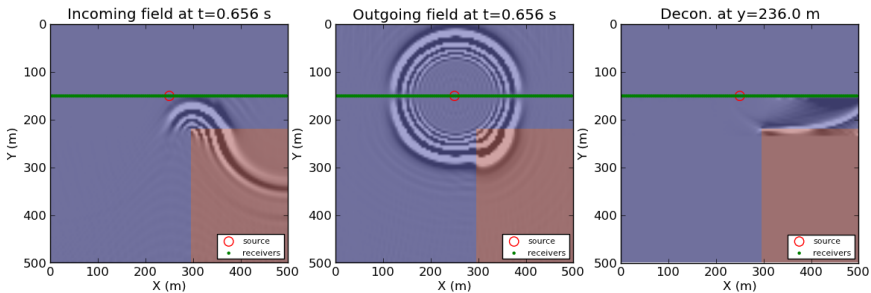
Ground-roll migration



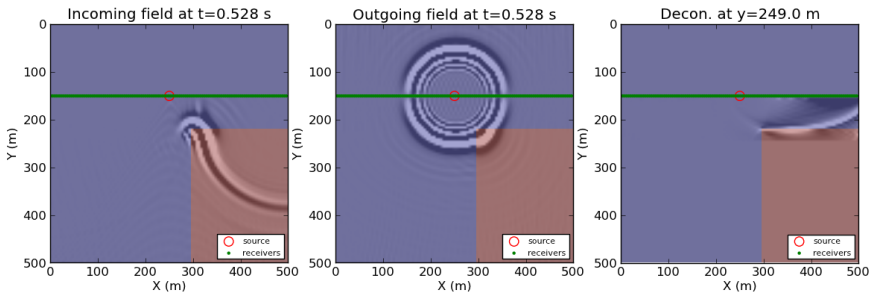
Ground-roll migration



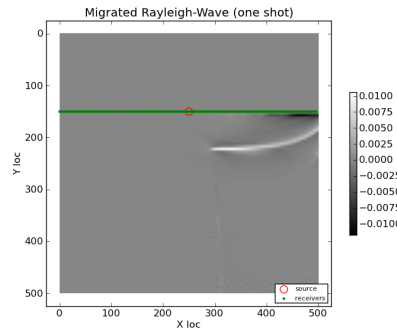
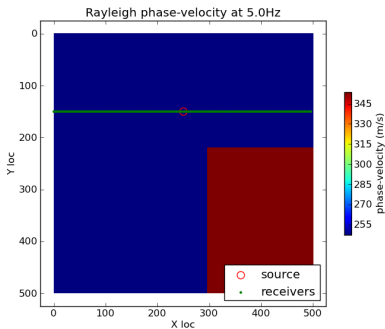
Ground-roll migration



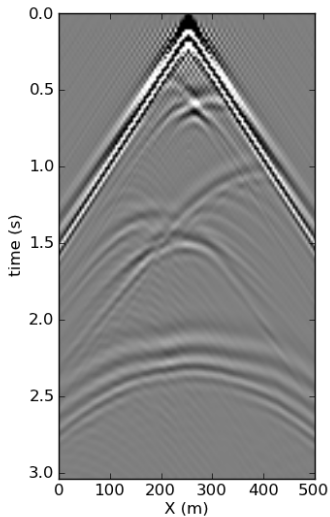
Ground-roll migration



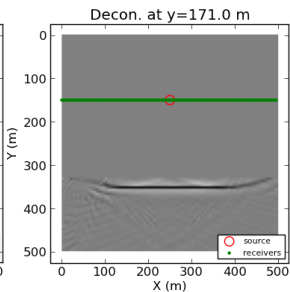
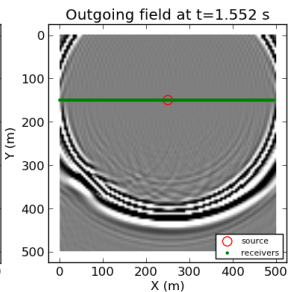
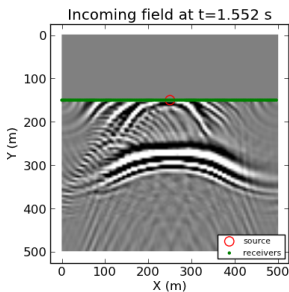
Ground-roll migration



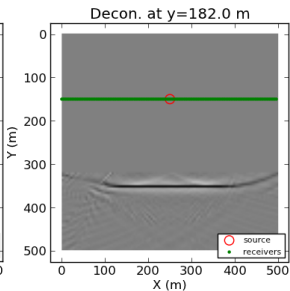
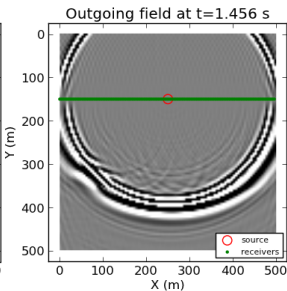
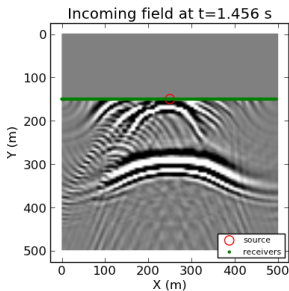
Ground-roll migration: 2



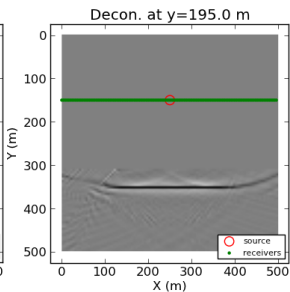
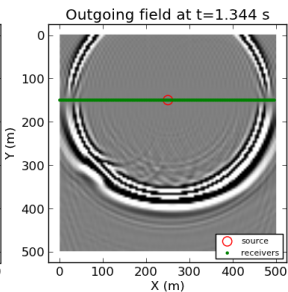
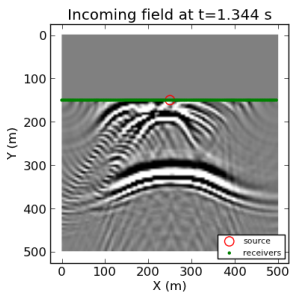
Ground-roll migration: 2



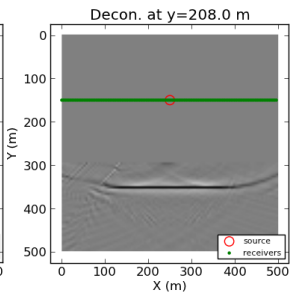
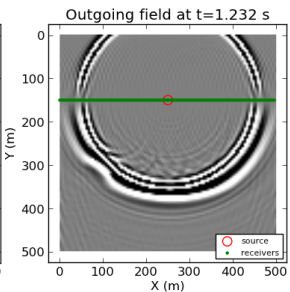
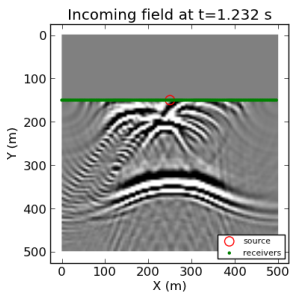
Ground-roll migration: 2



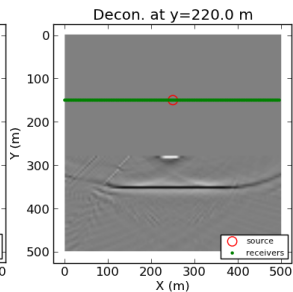
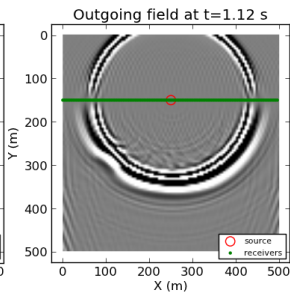
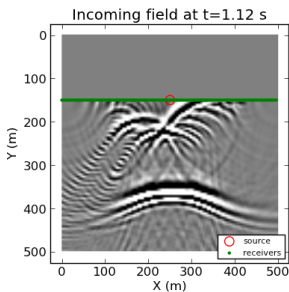
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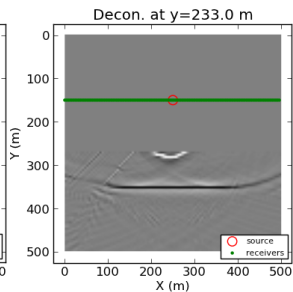
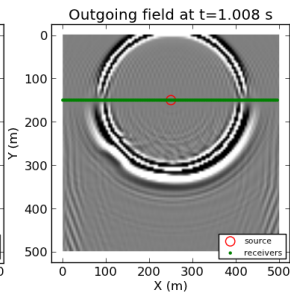
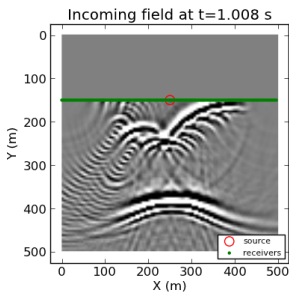
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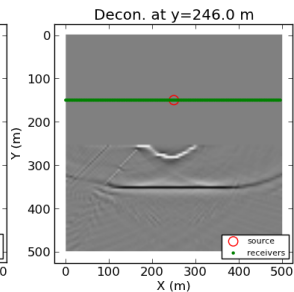
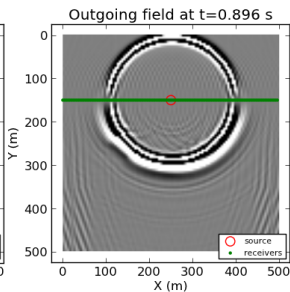
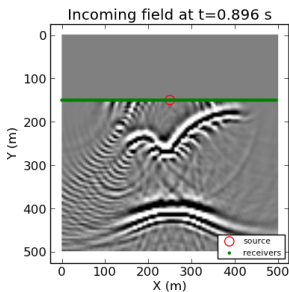
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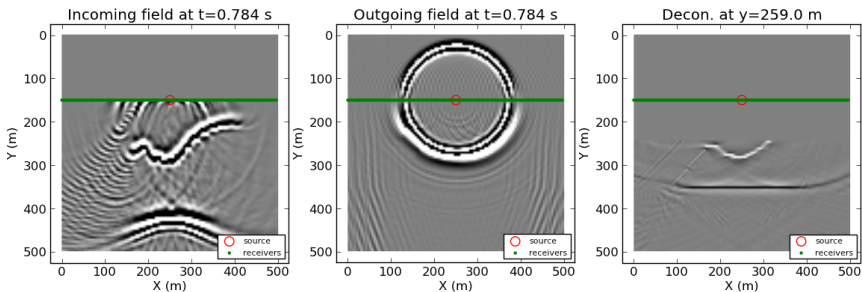
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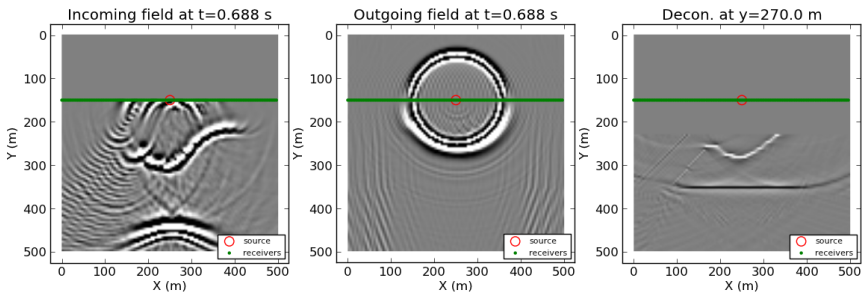
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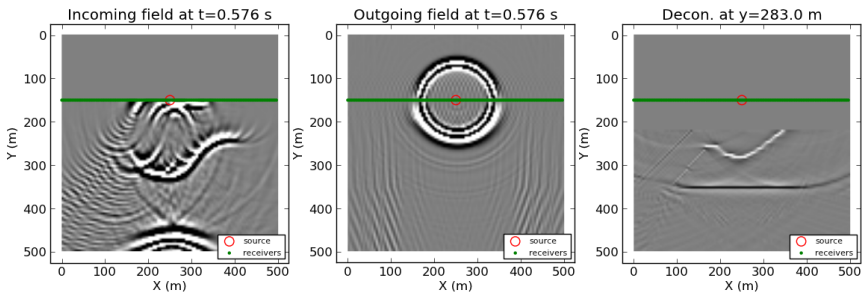
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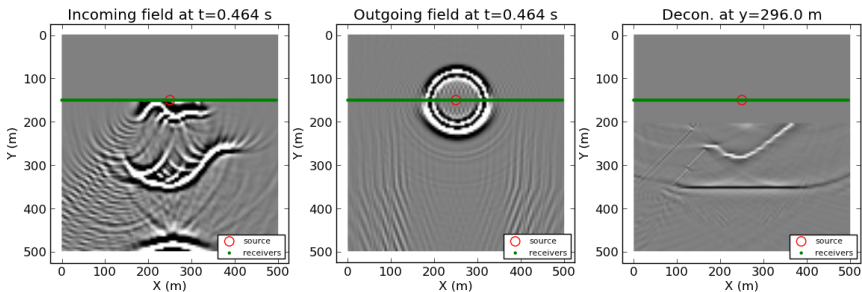
Ground-roll migration: 2



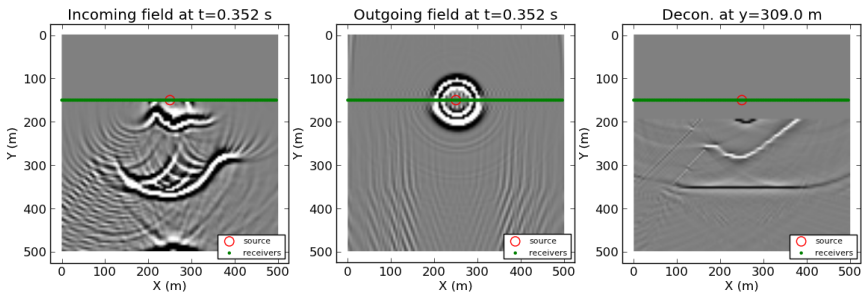
Ground-roll migration: 2



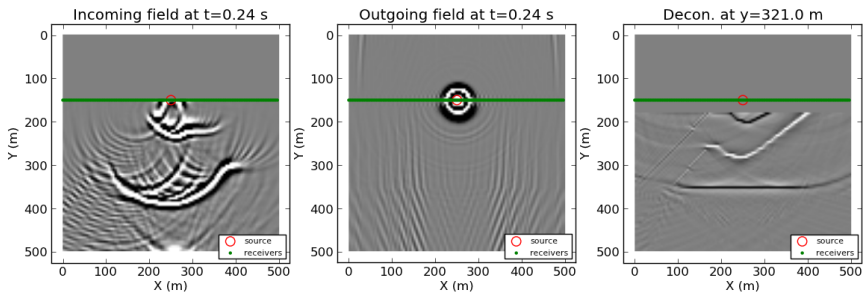
Ground-roll migration: 2



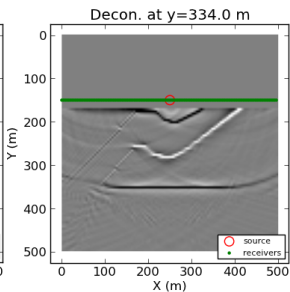
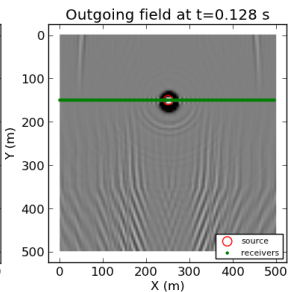
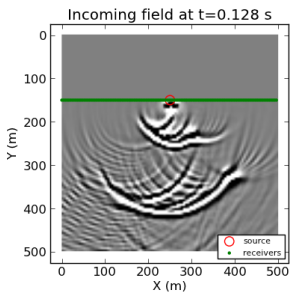
Ground-roll migration: 2



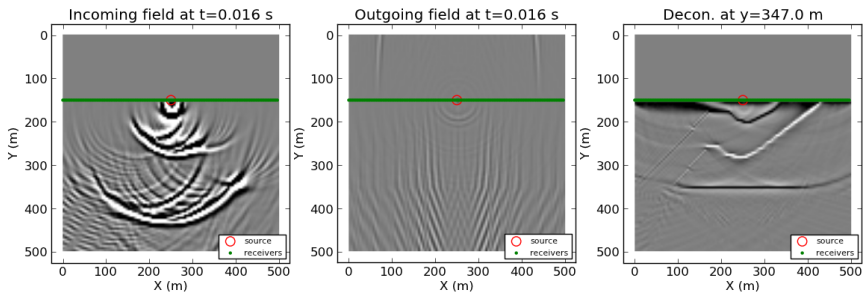
Ground-roll migration: 2



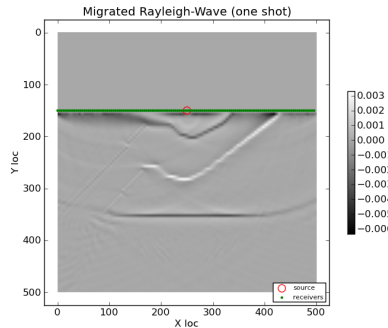
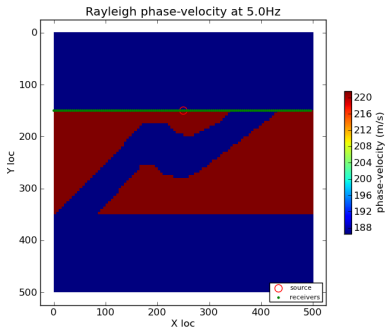
Ground-roll migration: 2



Ground-roll migration: 2



Depth imaging



Summary

- Near-surface is important to define.
 - Identifying faults.
 - Determining statics.
 - Designing filters.
- Useful information in back-reflected ground-roll.
 - Defines sharp lateral heterogeneity.
 - Frequency content adds depth dimension.
 - Deconvolution is effective in imaging faults from ground-roll.

Thank you

Frequency-to-depth: Mapping

Theory

Surface waves are most sensitive to the velocity structure at one-half the wavelength of the surface wave (Rix et. al., 1989). Likewise, surface waves are also most sensitive to reflectivity of the structure at one-half the wavelength.

